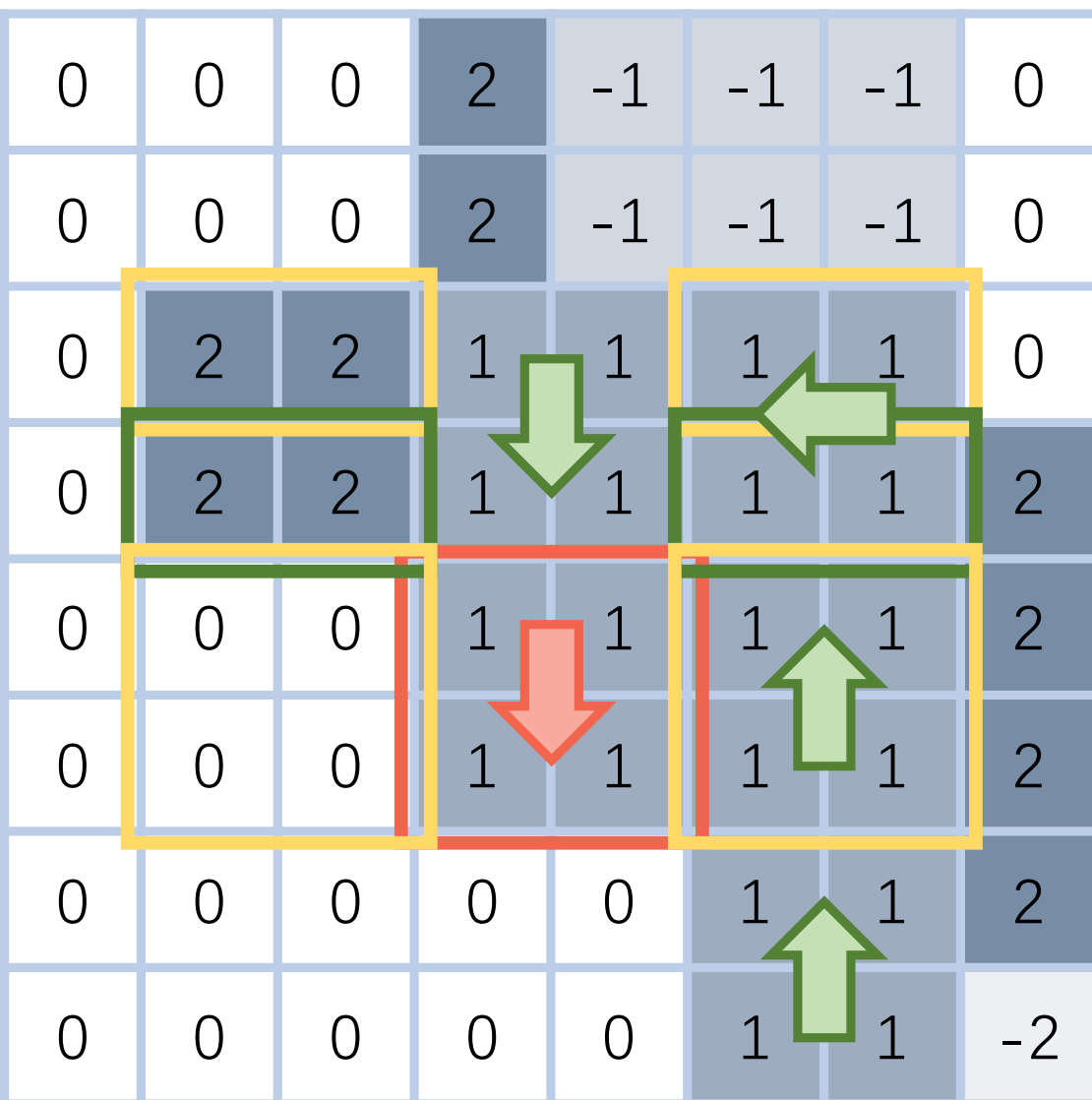


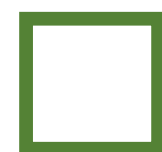
# 状态矩阵



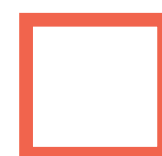
# 当前智能体朝向



## 之前智能体朝向



## 检查区域



## 当前区域

# 道路过宽判别矩阵

